

MatSat: a matrix-based differentiable SAT solver

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Matricized 3-SAT

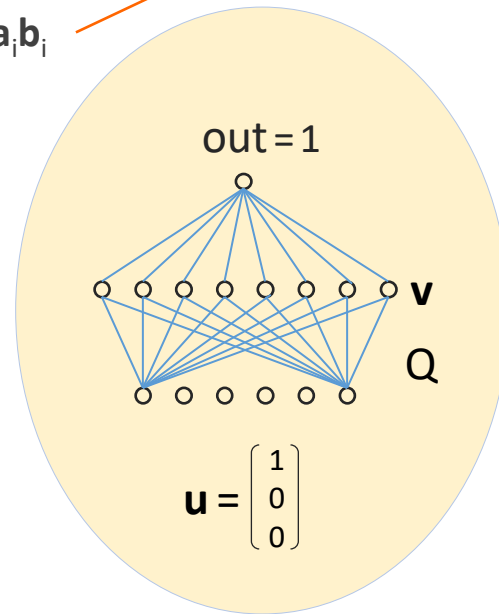
$$\bullet S = \{ \overbrace{a \vee b \vee \sim c}^{C_1}, \overbrace{a \vee \sim b}^{C_2} \}$$

$$Q = \begin{array}{c} \begin{array}{cccccc} a & b & c & \sim a & \sim b & \sim c \\ \hline 1 & 1 & 0 & 0 & 0 & 1 \\ 1 & 0 & 0 & 0 & 1 & 0 \\ \hline \end{array} \\ \begin{array}{cc} Q_1 & Q_2 \end{array} \end{array} \begin{array}{l} :C_1 \\ :C_2 \end{array}$$

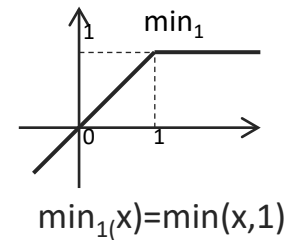
$$\mathbf{u} = \begin{bmatrix} 1 \\ 0 \\ 0 \end{bmatrix} \begin{array}{l} :a \\ :b \\ :c \end{array} \rightarrow \sim \mathbf{u} = \begin{bmatrix} 0 \\ 1 \\ 1 \end{bmatrix} \rightarrow \mathbf{u}^d = \begin{bmatrix} \mathbf{u} \\ \sim \mathbf{u} \end{bmatrix}$$

$$\begin{aligned} \mathbf{v} &= \min_1(Q\mathbf{u}^d) \\ &= \min_1((Q_1 - Q_2)\mathbf{u} + Q_1\mathbf{1}) \\ \text{out} &= (\mathbf{1} \bullet (\mathbf{1} - \mathbf{v})) < 1 \end{aligned}$$

$$(\mathbf{a} \bullet \mathbf{b}) = \sum_i a_i b_i$$



$$\min_1(Q\mathbf{u}^d) = \min_1 \left(\begin{bmatrix} 2 \\ 2 \end{bmatrix} \right) = \begin{bmatrix} 1 \\ 1 \end{bmatrix} \begin{array}{l} \rightarrow C_1 \text{ is true} \\ \rightarrow C_2 \text{ is true} \end{array} \rightarrow S \text{ is satisfiable}$$



SAT solving by minimizing J^{sat}

\mathbf{u} : real vector

#false clause

$(\mathbf{u} \odot (\mathbf{1} - \mathbf{u}))_i = u_i(1 - u_i)$

• $J^{\text{sat}} = \boxed{\mathbf{1} \cdot (\mathbf{1} - \min_1(\mathbf{Q}\mathbf{u}^d))} + \ell \|\mathbf{u} \odot (\mathbf{1} - \mathbf{u})\|^2$

• $J^{\text{sat}} = 0 \iff \mathbf{1} = \min_1(\mathbf{Q}\mathbf{u}^d) \text{ \& } \mathbf{u} \text{ is 0-1 vector}$

$\iff \mathbf{Q}\mathbf{u}^d \geq \mathbf{1} \text{ \& } \mathbf{u} \text{ is 0-1 vector}$

\iff every clause has at least one true literal

\iff S is satisfied by \mathbf{u}

All solutions are captured as a root of J^{sat}

Backpropagation for J^{sat}

- Jacobian $\mathbf{J}_a^{\text{sat}}$ of J^{sat}

- $\partial J^{\text{sat}} / \partial \mathbf{u}_p = (\mathbf{1} \cdot (-[\mathbf{c} < \mathbf{1}] \odot ((Q_1 - Q_2) \mathbf{l}_p))) + 2\ell ((\mathbf{u} \odot (\mathbf{1} - \mathbf{u}) \odot (\mathbf{1} - 2\mathbf{u})) \cdot \mathbf{l}_p)$
 $= ((- (Q_1 - Q_2)^T [\mathbf{c} < \mathbf{1}] + 2\ell (\mathbf{u} \odot (\mathbf{1} - \mathbf{u}) \odot (\mathbf{1} - 2\mathbf{u})) \cdot \mathbf{l}_p)$

where $\mathbf{l}_p = [0 \dots 1 \dots 0]^T$, $\mathbf{c} = Q\mathbf{u}^d$, $[\mathbf{c} < \mathbf{1}]_p = 1$ if $c_p < 1$, else = 0

- $\mathbf{J}_a^{\text{sat}} = - (Q_1 - Q_2)^T [\mathbf{c} < \mathbf{1}] + 2\ell (\mathbf{u} \odot (\mathbf{1} - \mathbf{u}) \odot (\mathbf{1} - 2\mathbf{u})) \approx \text{cubic polynomials}$

- Iterate (and binarize \mathbf{u} as a solution) until $J^{\text{sat}} = 0$

$$\mathbf{u} = \mathbf{u} - \alpha \mathbf{J}_a^{\text{sat}} = \mathbf{u} + \alpha Q_1^T [\mathbf{c} < \mathbf{1}] - \alpha Q_2^T [\mathbf{c} < \mathbf{1}] + \dots \quad O(mn)$$

- u_p is **increased** \propto | clauses falsified by \mathbf{u} having positive literal p |
- u_p is **decreased** \propto | clauses falsified by \mathbf{u} having negative literal $\sim p$ |

MatSat

- MatSat: **differentiable** SAT solver based on matrix
 - neither CDCL nor SLS but NN
 - finds satisfying assignments in a vector space by minimizing a cost function J^{sat} to zero (by Newton's method)
 - incomplete, cannot solve unsat problems
 - scalable by multi-threads, GPU → parallel SAT solver
 - some similarity to LP approach and SDP approach to MAX 2-SAT in continuous relaxation but much simpler and direct

MatSat algorithm

- MatSat is a new type of SAT solver

Algorithm 1: MatSat algorithm

Input: an instance matrix $\mathbf{Q} \in \{0, 1\}^{m \times 2n}$

for a SAT instance S , integers `max_try` and `max_itr`

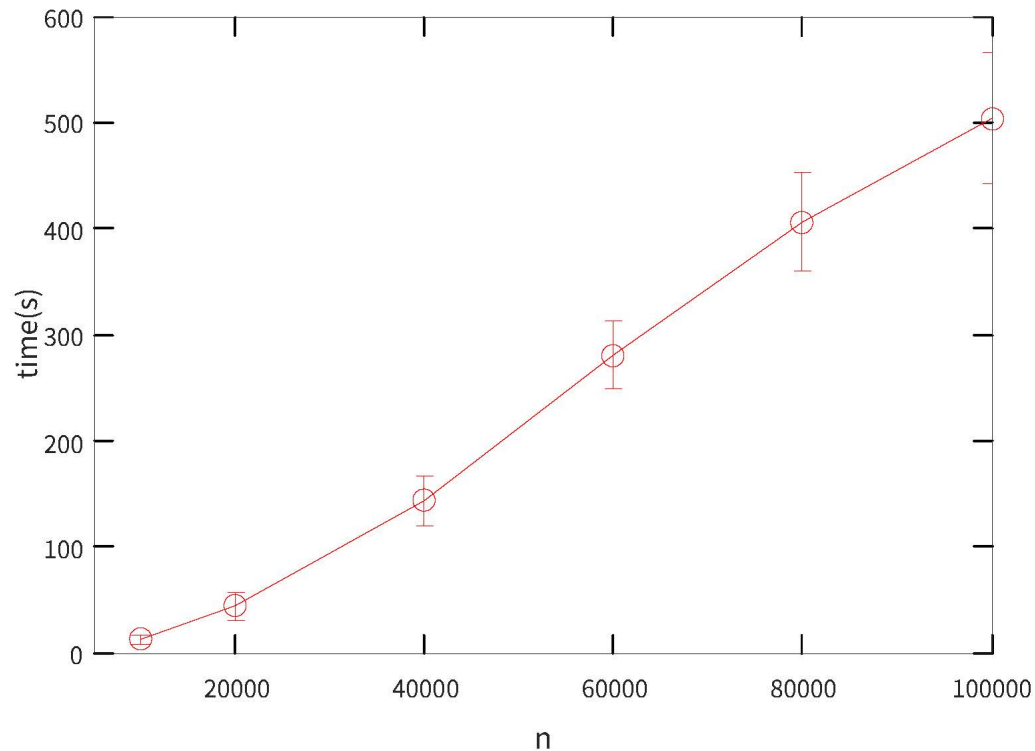
Output: an assignment vector \mathbf{u} for the variables in S and

error = the number of unsatisfying clauses by \mathbf{u}

- 1: initialize $\tilde{\mathbf{u}} \in \mathbb{R}^n$ by a uniform distribution $U(0,1)$
 - 2: **for** $p = 1$ **to** `max_try` **do**
 - 3: **for** $q = 1$ **to** `max_itr` **do**
 - 4: compute \mathbf{J}^{sat} by (1) and \mathbf{J}_{acb}^{sat} by (2)
 - 5: update $\tilde{\mathbf{u}}$ by (3)
 - 6: threshold $\tilde{\mathbf{u}}$ to a binary vector \mathbf{u} thresholding
 - 7: compute $error = \|\mathbf{I}_m - \min_1(\mathbf{Q}\mathbf{u}^d)\|_1$
 - 8: **if** $error = 0$ **then**
 - 9: exit p -loop
 - 10: **end if**
 - 11: **end for**
 - 12: $\tilde{\mathbf{u}} = (1 - \beta) \cdot \tilde{\mathbf{u}} + \beta \cdot \Delta$ % $0 < \beta < 1, \Delta \sim U(0,1)$ perturbation
 - 13: **end for**
 - 14: **return** \mathbf{u} and *error*
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MatSat_sp: Scalability

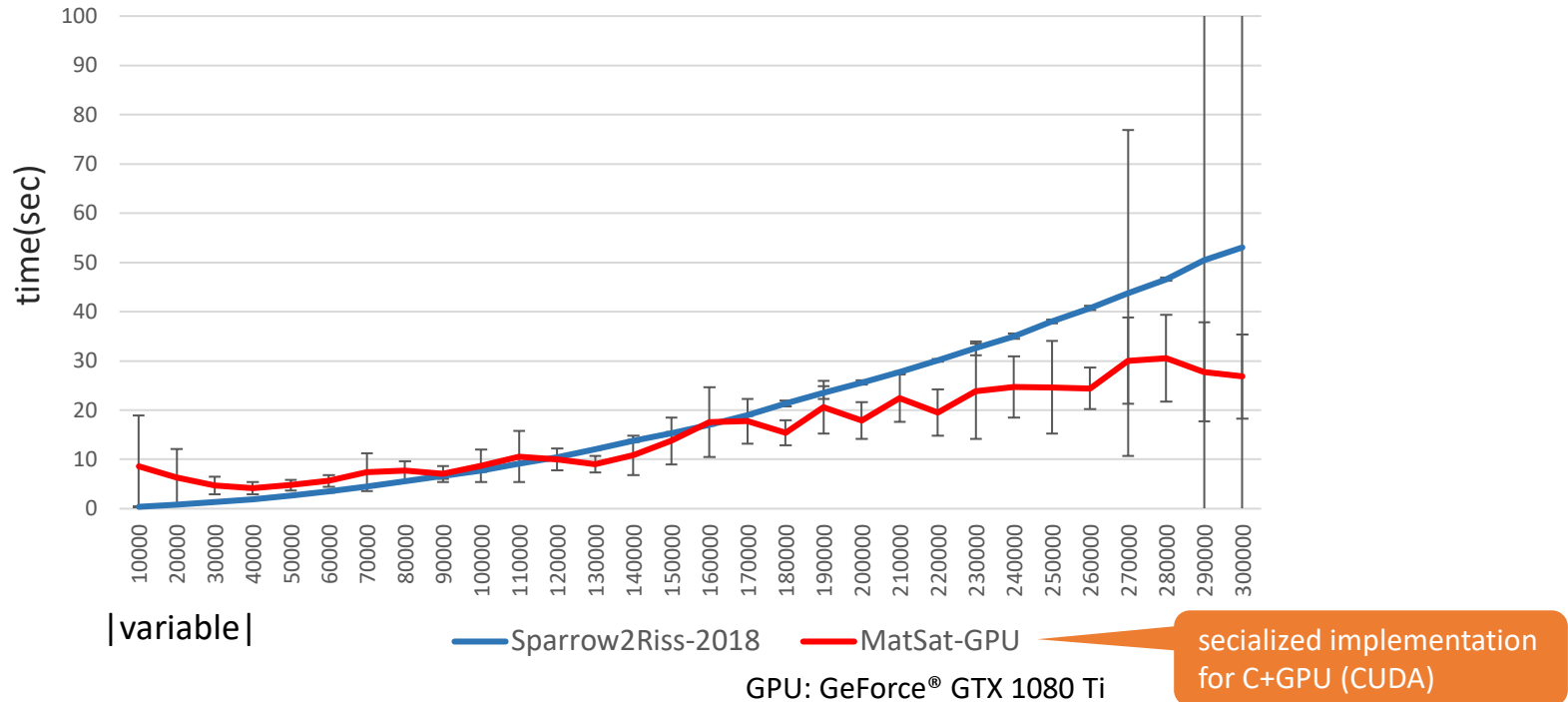
- Random 3-SAT ($|\text{var}| = n$, $|\text{clause}| = 4.26 * n$)



n	10000	20000	40000	60000	80000	100000
#instance	5	5	5	5	5	5

MatSat_sp (OpenMP) on PC with Intel Core i7-10700 CPU@2.90GHz, 16-threads
max_try = 100, max_itr = 1000, 5 trials on each instance (all error = 0)

MatSat-GPU: Large scale



|variable| = num. of variables

|clause|/|variable| = 4.26 fixed

Ave. time measured with $\pm\sigma$ over 10 trials with different seed
under the setting max_itr = 1000, max_try = 100

* 7 trials not converged in the whole trials

Comparison with SAT solvers

Random SAT

timeout=5000s

Solver		Data set			
		Set-A time(s)*	Set-B time(s)	Set-C time(s)* timeout/10	
	MatSat	0.0679	18.8	697.7	0/10
	Sparrow2Riss-2018	0.0013	2.3	1544.1	3/10
CDCL	gluHack	34.5	537.4	5000.0	10/10
	glucose-3.0_PADC_10_NoDRUP	42.9	962.4	5000.0	10/10
	MapleLCMDistChronoBT	0.34	519.1	5000.0	10/10
	MapleLCMDistChronoBT_DL_v3	1.96	762.3	5000.0	10/10
	MiniSat 2.2	3.28	50.1	5000.0	10/10
SLS	probSAT	0.0050	0.39	2134.8	2/10
	YalSAT	0.0058	0.34	1018.6	1/10
	CCAnr 1.1	0.0051	0.48	937.6	0/10

Set-A: 500 3-SAT instances generated as uniform random SAT

Set-B: /rnd-barthel (<http://sat2018.forsyte.tuwien.ac.at/benchmarks/Random.zip>)

Set-C: /Balint (<http://sat2018.forsyte.tuwien.ac.at/benchmarks/Random.zip>)

SAT Competition 2018

Random SAT Track: learning time(s)

	Set-B rnd-barthel 3-SAT (55 inst)	Set-C Balint 5-SAT (10 inst)		Set-H rnd-qhid 3-SAT (55 inst)		Set-I rnd-komb 3-SAT (55 inst)	
	time(s)/inst.	time/inst.	timeout (5000s)	time(s)/inst.	timeout (200s)	time(s)/inst.	timeout (200s)
MatSat_sp	18.8	697.7	0/10	59.6	12/55	193.6	51/55
max_(itr try)	(500 100)	(2k 5k)		(1k 100)		(2k 100k)	
S2R	2.3	1544.1	3/10	127.7	42/55	1.0	0/55
probSAT	0.39	2134.8	2/10	156.3	43/55	172.8	47/55
YaISAT	0.34	1018.6	1/10	156.3	43/55	178.1	50/55
CCAnr11	0.48	937.6	0/10	777.9	38/55	55.0	8/55

<http://sat2018.forsyte.tuwien.ac.at/benchmarks/Random.zip>

Non-random SAT(Set-{D,E})

		Solver	Data set		
			Set-D time(s)	Set-E time(s)	Set-F time(s)* timeout/20
CDCL		MatSat	9.29	679.7	2.0 0/20
		Sparrow2Riss-2018	0.23	0.26	251.9 1/20
		gluHack	0.32	0.58	5000.0 20/20
		glucose-3.0_PADC_10_NoDRUP	0.45	0.63	4346.2 17/20
		MapleLCMDistChronoBT	0.22	0.42	3643.7 12/20
		MapleLCMDistChronoBT_DL_v3	0.24	0.42	3205.7 10/20
SLS		MiniSat 2.2	0.21	0.21	4345.8 15/20
		probSAT	0.46	0.46	14.3 0/20
		YalSAT	0.39	0.45	41.3 0/20
		CCAnr1.1	0.39	0.50	14.2 0/20

	Set-D	Set-E	Set-F
k-SAT	3-SAT (100 inst)	5-SAT (100 inst)	5-SAT (20 inst)
(n m)	(90 300)	(500 3100)	(320 1120)

timeout=5000s

Set-D: SATLIB_FlatGraph/Flat30-60 (<https://www.cs.ubc.ca/~hoos/SATLIB/benchm.html>)

Set-E: SATLIB_MorphGraph/SW100-8-0 (<https://www.cs.ubc.ca/~hoos/SATLIB/benchm.html>)

Set-F: SAT2018_benchmark_Main_cnf/Jingchao_Chen (<http://sat2018.forsyte.tuwien.ac.at/benchmarks/index.html>)

Weighted variables and clauses

- MatSat performs poorly on non-random SAT
- Introduce variable weight $\mathbf{w}(v)$ and clause weight $\mathbf{w}(c)$ to simulate prioritized optimization of variables (just like unit propagation)

$\mathbf{w}(v) = (\text{num. of variable } v\text{'s occ. in the SAT instance}) / (\text{ave. var. weight})$

$$\rightarrow \mathbf{w}_v = [\mathbf{w}(v_1) \cdots \mathbf{w}(v_n)]^T$$

$\mathbf{w}(c) = \text{sum of variable weights in a clause } c$

$$\rightarrow \mathbf{w}_c = [\mathbf{w}(c_1) \cdots \mathbf{w}(c_m)]^T$$

- Define weighted $J^{\text{sat-w}}$ and compute Jacobian $\mathbf{J}_a^{\text{sat-w}}$ as

$$J^{\text{sat-w}} = (\mathbf{1} \bullet \mathbf{w}_c \odot (\mathbf{1} - \min_1(\mathbf{Q}\mathbf{u}^d))) + \ell \|\mathbf{w}_v \odot \mathbf{u} \odot (\mathbf{1} - \mathbf{u})\|^2$$

$$\mathbf{J}_a^{\text{sat-w}} = -(\mathbf{Q}_1 - \mathbf{Q}_2)^T [\mathbf{w}_c \odot (\mathbf{Q}\mathbf{u}^d \leq 1)] + 2\ell (\mathbf{w}_v \odot \mathbf{w}_v \odot \mathbf{u} \odot (\mathbf{1} - \mathbf{u}) \odot (\mathbf{1} - 2\mathbf{u}))$$

Weighted MatSat: learning time(s)

- The weighted version runs much faster (as far as Set-{D,E,G} concerned)

MatSat_sp	Set-D 3-SAT (100 inst)	Set-E 5-SAT (100 inst)	Set-G 5-SAT (100 inst)
non-weighted	9.29	679.7	1277.3
max_(itr try)	(500 100)	(2k 100)	(5k 100)
weighted	2.18	82.4	123.7
max_(itr try)	(100 300)	(1k 100)	(200 100)

Set-G: SATLIB MorphGraph/sw100-8-lp1-c5 (<https://www.cs.ubc.ca/~hoos/SATLIB/benchm.html>)

Conclusion

- MatSat is a new type of SAT solver based on matrix
 - solution search by cost minimization in a vector space
 - NN with a single layer for logical operations
 - seems competitive w.r.t. random SAT
 - declarative, simple and scalable (by many-cores and GPUs)
 - under development for improvement
 - variable, clause weight, dynamic weighting
 - ℓ_1 norm, activating function etc
- Structured problems are hard → future challenge
- Extending to weighted MAX-SAT is straightforward

$$J^{\text{max-sat}} = (\mathbf{w} \cdot (\mathbf{1} - \min_1(\mathbf{Q}\mathbf{u}^d))) + \dots$$